A SENSITIVITY ANALYSIS AND AN IMPLEMENTATION OF THE WELL-KNOWN VOGEL'S APPROXIMATION METHOD FOR SOLVING UNBALANCED TRANSPORTATION PROBLEM

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ABSTRACT Though, in the literature, many heuristic approaches were developed in getting an initial solution, VAM (Vogel's approximation method) is considered to be a better efficient heuristic approach since it often provides an optimal or near optimal solution to the transportation problem. In general, transportation problems involved in supply-chain management fields are unbalanced (total supply > total demand or total supply < total demand) and large-scale problem size. Always, an unbalanced transportation problem is balanced before VAM procedure is applied. But, sometimes, using VAM with unbalanced feature can provide an improved VAM solution. To study this, a sensitivity analysis of VAM has been performed. Based on the sensitivity analysis of VAM, we can conclude that when we solve an unbalanced transportation problem using VAM procedure it is vital to solve the unbalanced transportation problem both ways with balancing and without balancing to get the initial costs of VAM and take the better one as the initial cost to the considered unbalanced transportation problem. Further, in solving large-scale transportation problems, an implementation of VAM is preferred due to time-consuming computations of VAM. In this paper, an attempt has been made to implement the coding of VAM successfully using C++ and compared to the existing coding of VAM from Nabendu Sen et al. [12] via many numerical examples. Based on the results of numerical examples, we can conclude that the correctness of the newly coded VAM is promising as compared with the previously coded one by Nabendu Sen et al. [12].

Keywords: Transportation problem, Vogel's approximation method, Heuristic approach, Initial solution.

INTRODUCTION

The transportation problem is a special class of linear programming problem that deals with shipping a product from multiple origins to multiple destinations. The objective of the transportation problem is to find a feasible way of transporting the shipments to meet demand of each destination that minimizes the total transportation cost while satisfying the supply and demand constrains.

Due to time-consuming computations of the simplex method (for more detail, refer to Reeb and Leavengood [1]), the transportation method is preferred in solving transportation problems. Determination of the initial basic feasible solution (IBFS) and checking its optimality are the two basic steps of the transportation method. That is, all the optimal solution approaches (e.g., stepping stone method – Charnes and cooper [2], modified distribution method – Dantzig [3], etc) in solving transportation problems need an IBFS to get the optimal solution. Though, in the

literature, many heuristic approaches were developed in getting an initial solution, such as Northwest corner method (Taha Hamdy [4]), minimum cost method (Taha Hamdy [4]), VAM - Vogel's approximation method (Reinfeld and Vogel [5]), etc, VAM is considered to be a better heuristic approach. Shweta Singh et al. [6] improved VAM by using total opportunity cost and regarding alternative allocation cost. Goval [7] improved the VAM procedure for solving unbalanced transportation problems. Saleem and Imad [8] proposed a hybrid two-stage algorithm to find the optimal solution for transportation problem. Edward Samuel [9] improved the zero point method in solving both crisp and fuzzy transportation problems. Susann et al. [10] analyzed degeneracy characterizations for two classical problems. Kulkarni and Datar [11] proposed a heuristic method of obtaining an initial basic feasible solution (IBFS) to solve modified unbalanced transportation problem. Five methods namely northwest corner method, minimum cost method, row minimum cost method, column minimum cost method and VAM were coded in C++ by Nabendu Sen et al. [12] for solving transportation problem. We found that the object oriented program of VAM given by Nabendu Sen et al. [12] for solving transportation problem is not correctly coded. This is checked with many randomly generated problem instances and found that his coding worked for none. In this paper the coding of VAM is implemented in C++. Then its correctness is verified via many randomly generated instances. In addition to that a sensitivity analysis has been performed on wellknown VAM procedure to see the influence of balancing and unbalancing issues on the initial cost solution of VAM obtained by solving unbalanced transportation problem.

The remainder of this paper is organized as follows: Section 2 deals with the mathematical formulation of the transportation problem. In section 3 the well-known VAM procedure is summarized. Section 4 deals with sensitivity analysis of VAM. In Section 5 potential significance of the developed object oriented programming of VAM is illustrated with a numerical example. Finally, conclusion by highlighting the limitations and future research scope on the topic is made in section 6.

MATHEMATICAL STATEMENT OF THE TRANSPORTATION PROBLEM

In developing the LP model of the transportation problem the following notations are used :

- a_i Amounts to be shipped from shipping origin $i(a_i \ge 0)$.
- b_i Amounts to be received at destination j ($b_i \ge 0$).
- $C_{i,i}$ Shipping cost per unit from origin *i* to destination $j(c_{i,i} > 0)$
- $x_{i,j}$ Amounts to be shipped from origin *i* to destination *j* to minimize the total cost ($x_{i,j} \ge 0$).

We assume that the total amount shipped is greater than or equal to the total amount received, that is,

$$\sum_{i=1}^{m} a_i \ge \sum_{j=1}^{n} b_j$$

Transportation Problem

$$\operatorname{Min} \sum_{i=1}^{m} \sum_{j=1}^{n} c_{ij} x_{ij}$$

Subject to $\sum_{j=1}^{n} x_{ij} \leq a_{i}$, $i=1,2,...,m$ (1)

$$\sum_{i=1}^{m} x_{ij} = b_j , j=1,2,...,n$$

where
$$x_{ij} \ge 0 \forall i, j$$
.

VOGEL'S APPROXIMATION METHOD (VAM)

The steps involved in VAM in producing the initial feasible solution are described below:

Step 0: Balance the given transportation problem if either (total supply > total demand) or (total supply < total demand).

- **Step 1:** For each row and column of the transportation table, determine the difference between the least and the next least shipping costs.
- **Step 2:** Select the row or column with the largest difference (breaking ties arbitrarily).
- Step 3: Assign as many units as possible to the least cost square in the row or column selected.
- **Step 4:** Eliminate any row or column that has completely been satisfied by the assignment just made.
- **Step 5:** Recalculate the cost differences omitting rows or columns already crossed out in the preceding step.
- **Step 6:** Move to step 2 and repeat the steps 2 5 until an initial feasible solution has been obtained.

SENSITIVITY ANALYSIS

In General, before VAM procedure is applied to solve the unbalanced transportation problems,

the problem has to be balanced first by adding a dummy column (if total supply > total demand) or dummy row (if total supply < total demand). In this section, an attempt has been taken to use VAM procedure for solving the unbalanced transportation problem first by balancing and then without balancing it. Following this, we found that in certain circumstances, balancing is a must before VAM procedure is applied for solving unbalanced transportation problems. In contrast, there are also certain circumstances, where balancing not to be done before VAM is applied. This is illustrated by following two unbalanced transportation problems taken from previous journal papers.

Problem 1

The following 5 x 4 numerical problem from Nabendu Sen et al. [12] is used to illustrate whether balancing a unbalanced transportation problem is vital or not.

Table 1 The cost matrix table of Nabendu Sen et al. [12]

From /	b_1	b_2	b ₃	b_4	Supply
10					
a ₁	60	120	75	180	8000
a_2	58	100	60	165	9200
a ₃	62	110	65	170	6250
a_4	65	115	80	175	4900
a_5	70	135	85	195	6100
Demand	5000	2000	10000	6000	34,450 / 23,000

(i) VAM is used after balancing the problem

Table 2 The Balanced cost matrix (by the addition of
dummy column b5) for table 1

From /	b ₁	b ₂	b ₃	b_4	b ₅	Supply
a_1	60	120	75	180	0	8000
a_2	58	100	60	165	0	9200
a_3	62	110	65	170	0	6250
a_4	65	115	80	175	0	4900
a ₅	70	135	85	195	0	6100
Demand	5000	2000	10000	6000	11450	34,450 / 34,450

Table 3	The	VAN	1 initial	l cost a	allocat	ions f	for the	÷
	prob	olem i	from N	abend	u Sen	et al.	[12]	

P	1001011	nomin	ac en a a s	en et an		
From /	b ₁	\mathbf{b}_2	b ₃	\mathbf{b}_4	b ₅	Supply
То						
a 1	60	120	75	180	0	
~1	5000		3000			8000
ลา	58	100	60	165	0	0000
u 2		2000	1200	6000		9200
9.	62	110	65	170	0	
az			5800		450	6250
9	65	115	80	175	0	
a ₄					4900	4900
9-	70	135	85	195	0	1900
a ₅					6100	6100
Demand	5000	2000	10000	6000	11450	34,450 /
						34,450

The associated initial cost for the problem from Nabendu Sen et al. [12] obtained from **table 3** is 2,164,000. It should be noted that in Nabendu Sen et al. [12], for the same problem this cost is 1,273,000 which is incorrect. This 1,273,000 should be corrected as 2,164,000. However, the optimal cost for this problem is 2,146,750.

(ii) VAM is used without balancing the problem

Table 4	The	VAM	initial	cost a	allocat	ions f	for the
	prot	olem fi	rom Na	abend	u Sen	et al.	[12]

From / To	b 1	\mathbf{b}_2	b ₃	b ₄	Supply
8.	60	120	75	180	
••1	5000		3000		8000
ลา	58	100	60	165	0000
u 2		2000			9200
82	62	110	65	170	/200
uj			900	1100	6250
я.	65	115	80	175	
u 4				4900	4900
a-	70	135	85	195	1900
us			6100		6100
Demand	5000	2000	10000	6000	34,450 / 23,000

The associated initial cost for the same problem from Nabendu Sen et al. [12] obtained from **table 4** is 2,346,500.

Problem 2

The following 4 x 3 numerical problem from Kulkarni & Datar [11] is used to illustrate whether balancing an unbalanced transportation problem is vital or not.

Table 5 The cost matrix table of Kulkarni &

D	atar [11]			
From / To	\mathbf{b}_1	b ₂	b ₃	Supply
a ₁	3	4	6	100
a ₂	6	3	5	80
a ₃	7	4	2	90
a4		-	-	120
Demand	110	110	60	390 / 280

(i) VAM is used after balancing the problem

Table 6 The Balanced cost matrix (by the additionof dummy column b5) for table 5

From / To	b ₁	\mathbf{b}_2	b ₃	b 4	Supply
\mathbf{a}_1	3	4	6	0	100
a ₂	7	3	8	0	80
a ₃	6	4	5	0	00
\mathbf{a}_4	7	5	2	0	90
					120
Demand	110	110	60	110	390 / 390

 Table 7 The VAM initial cost allocations for the problem from Kulkarni & Datar [11]

problem nom Kutkarni & Datar [11]								
From /	$\mathbf{b_1}$	\mathbf{b}_2	b ₃	\mathbf{b}_4	Supply			
То								
a ₁	3	4	6	0				
1	100				100			
a 2	7	3	8	0				
2		80			80			
9.	6	4	5	0	00			
uj				90	90			
э.	7	5	2	0	20			
a 4	10	30	60	20	120			
Demand	110	110	60	110	390 / 390			

The associated initial cost for the problem from Kulkarni & Datar [11] obtained from **table 7** is 880.

(ii) VAM is used without balancing the problem

Table 8	The VAM initial cost allocations for the
	problem from Kulkarni & Datar [11]

From /	b ₁	b ₂	b ₃	Supply
То				
\mathbf{a}_1	3	4	6	
-	100			100
82	7	3	8	
u 2		80		80
9.	6	4	5	
az		30		90
8.	7	5	2	20
••4	10		60	120
Demand	110	110	60	390 / 280

The associated initial cost for the same problem from Kulkarni & Datar [11] obtained **from table 8** is 850.

However, the optimal cost for problem 1 and Problem 2 are 2,146,750 and 840 respectively.

The **Figure 1** represents that if problem 1 is balanced before VAM procedure is applied then the initial cost of problem 1 obtained by VAM procedure is much closer to the optimal cost than in case of unbalancing. In contrast, the Figure 2 represents that if problem 2 is balanced before VAM procedure is applied then the initial cost of problem 2 obtained by VAM procedure is much far to the optimal cost than in case of unbalancing. Thus, by balancing problem 1 we can get a better VAM cost solution with less deviation from its optimal cost. In contrast, without balancing problem 2 we can get a better VAM cost solution with less deviation from its optimal cost (see Fig.3 and Table 9). Hence, it is much better to balance the problem1 and not to balance the problem2 before VAM procedure is used. Therefore, when we solve an unbalanced transportation problem using VAM procedure it is vital to solve the same unbalanced transportation problem both ways with balancing and without balancing. Since, VAM procedure is coded in C++ this task can be easily done with coded VAM.

Problems	Authors	VAM initial cost		AM initial cost Deviation from the optimal cost (%)		Optimal Cost	
		By Balancing	Without Balancing	VAM cost by balancing	VAM cost without Balancing		
1	Nabendu Sen et al. [12]	2,164,000	2,346,500	0.80	9.30	2,146,750	
2	Kulkarni & Datar [11]	880	850	4.80	1.20	840	
2400000 2350000 2300000 2250000		■ VAM cost balancing problem	t by the	890 880 870 870		■ VAM cost by balancing the problem	

Table 9 The closeness of VAM initial cost to the optimal cost in case of balancing and unbalancing the unbalanced transportation problems











NUMERICAL ILLUSTRATION

The following 6 numerical examples taken from previous papers shown in **Table 10** and the 5 randomly generated ones shown in **table 11** are used to show the potential significant of the developed Object Oriented Programming (ORP) of VAM in this paper.

Table 10 The initial costs of 6 numerical
examples obtained using Object Oriented
Programming (ORP) of VAM in this
paper and in Nabendu Sen et al. [12]

		VAM initial cost obtained by running the ORP Nabendu	
Examples	Authors		
		This	Sen et al.
		Paper	[12]
	Raeeb, J &		
1	Leavengood, S.	4400	-
	[1]		
	Shweta Singh,		
2	G. C. et al. [6]	2323	-
	Goyal, S.K. [7]		
3		1745	-
	Saleem, Z.R		
4	and Imad, Z.R	5600	-
	[8]		
	Edward		
5	Samuel, A. [9]	28	-
	Susann Schrenk		
6	et al. [10]	59	-

Table 11 The VAM initial costs of 5 randomly
generated examples obtained using Object
Oriented Programming (ORP) of VAM in
this paper and in Nabendu Sen et al. [12]

Examples	Problem	VAM initial cost obtained by running the ORP	
	Size (mxn)	This Paper	Nabendu Sen et al. [12]
1	5 x 10	31, 160	-
2	5 x 10	3541	-
3	10 x 15	1669	-
4	10 x 20	878493	-
5	10 x 20	4836	-

Both **Tables 10 & 11** represent that the developed Object Oriented Programming of

VAM (coded VAM) in this paper worked for all the examples considered. In contrast, the Object Oriented Programming of VAM proposed by Nabendu Sen et al. [12] worked for none of the example considered in table 10 and table 11. That is, if we use the coded VAM of Nabendu Sen et al. [12] then we will not be able to get any solution for the examples from table 10 and table 11. In addition to this, Both our coded VAM and the coded VAM of Nabendu Sen et al. [12] were tested with many other examples and found that even though our one give the exact VAM solutions, Nabendu Sen et al. [12] does not. Due to space consideration, the detail of the all five randomly generated examples and the developed object oriented programming of well-known VAM (our coded VAM) for solving transportation problems are not given in this paper and are available from the author.

CONCLUSION

In this paper, the coding of well-known VAM is successfully implemented using C++ and its correctness is tested via many randomly generated problem instances and six numerical examples taken from previous papers. Based on these results we can conclude that the correctness of the newly coded VAM is promising as compared with the previously coded one by Nabendu Sen et al. [12]. Moreover, a sensitivity analysis has been performed on VAM procedure to see the influence of balancing and unbalancing issues on the initial cost of VAM. We found in certain circumstance, the obtained initial solution by VAM via balancing can be improved if no balancing is done on the unbalanced problem before using VAM. In contrast, we found in the other certain circumstance, the obtained initial solution by VAM via unbalancing can be improved if balancing is done on the unbalanced problem before using VAM. Therefore, when we solve an unbalanced transportation problem using VAM procedure it is vital to solve the same unbalanced transportation problem in both ways with balancing and without balancing. Then by comparing initial cost of VAM obtained in both ways, we can take the better one as the initial cost to the considered unbalanced transportation problem. Since, VAM procedure is coded in C++ this task can be easily done with coded VAM of this paper. Future research might be carried out in proposing an efficient better solution procedure which can provide a better solution than VAM for solving initial

transportation problems. We intend to devote ourselves in this direction.

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